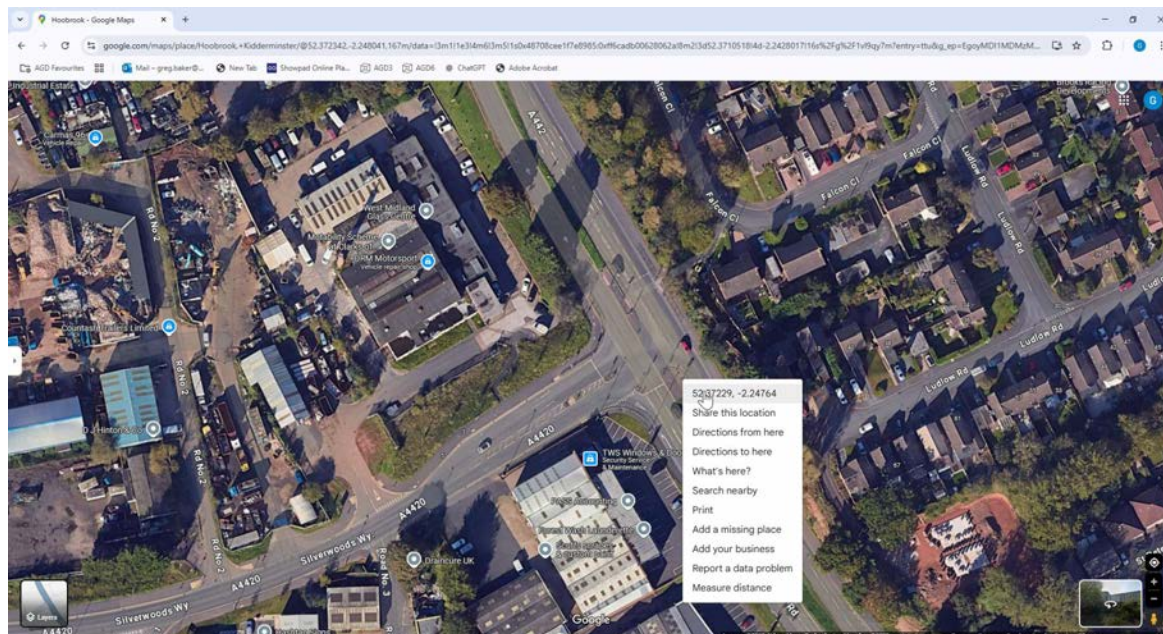


AGD352



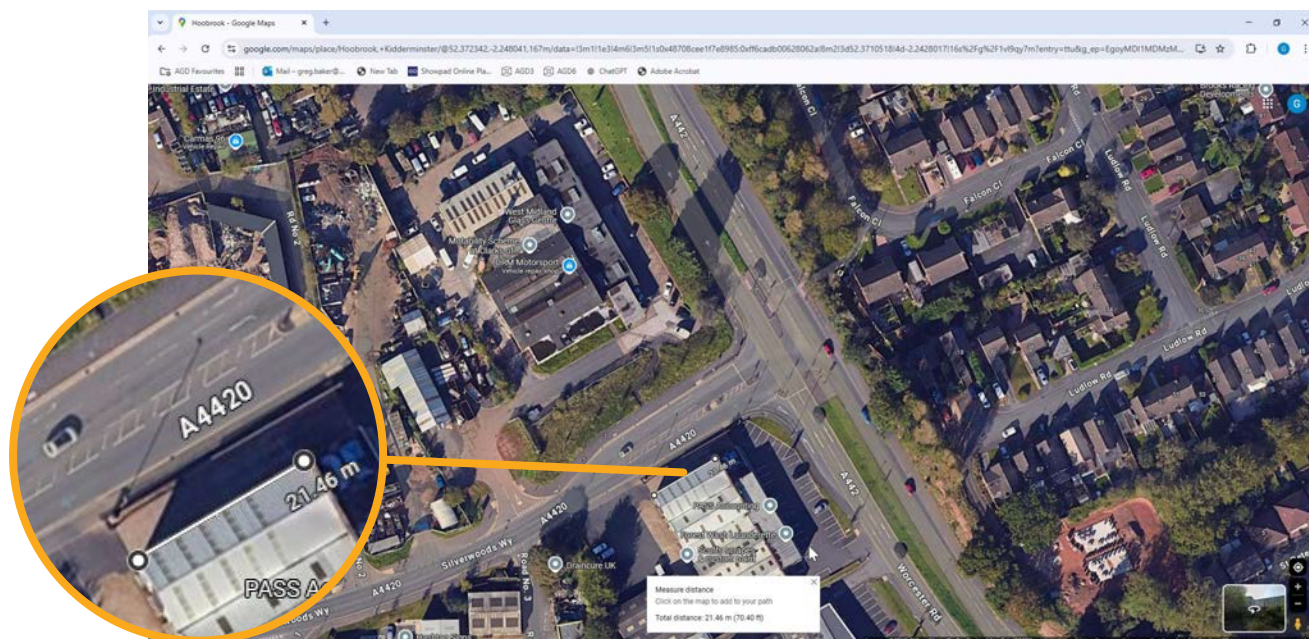
Traffic Manager Configuration Guide

Using Google Maps to capture the desired location, right click point of interest on the map where you wish to use the AGD352 radar to obtain the LAT/LON. Make a note of this reference.



To configure Traffic Manager with accurate measurements, right click on Google maps to measure the distance between two points.. We recommend using a permanent feature such as a building for this measurement.

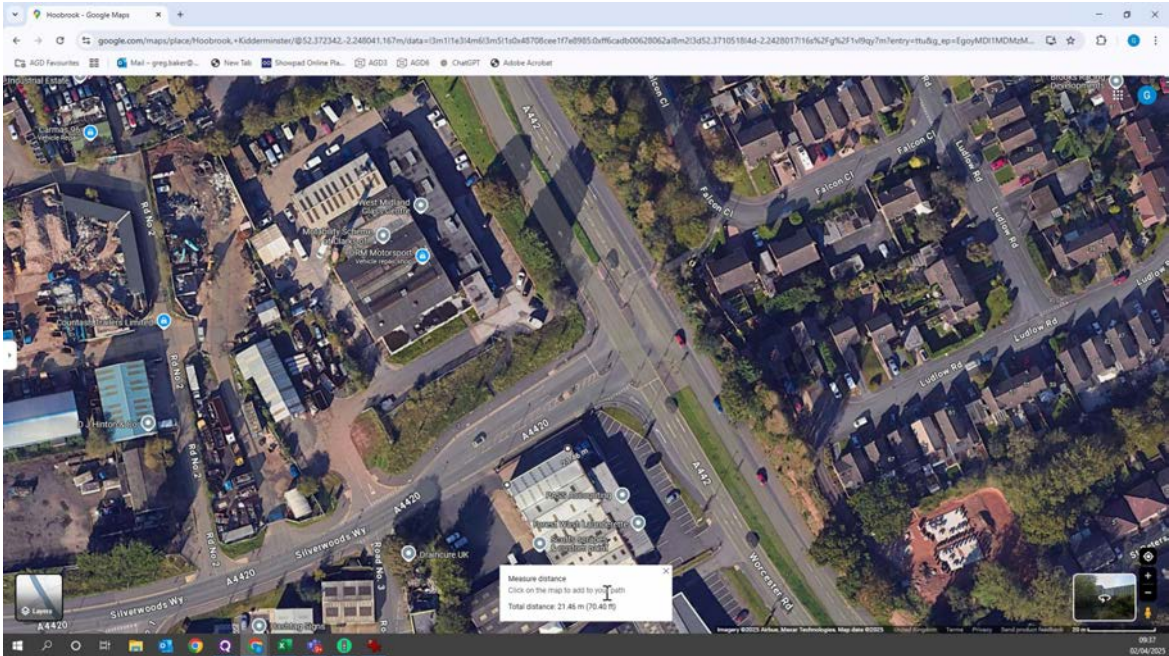
Hint: Google maps does have proven accuracy.



CONFIGURATION GUIDE

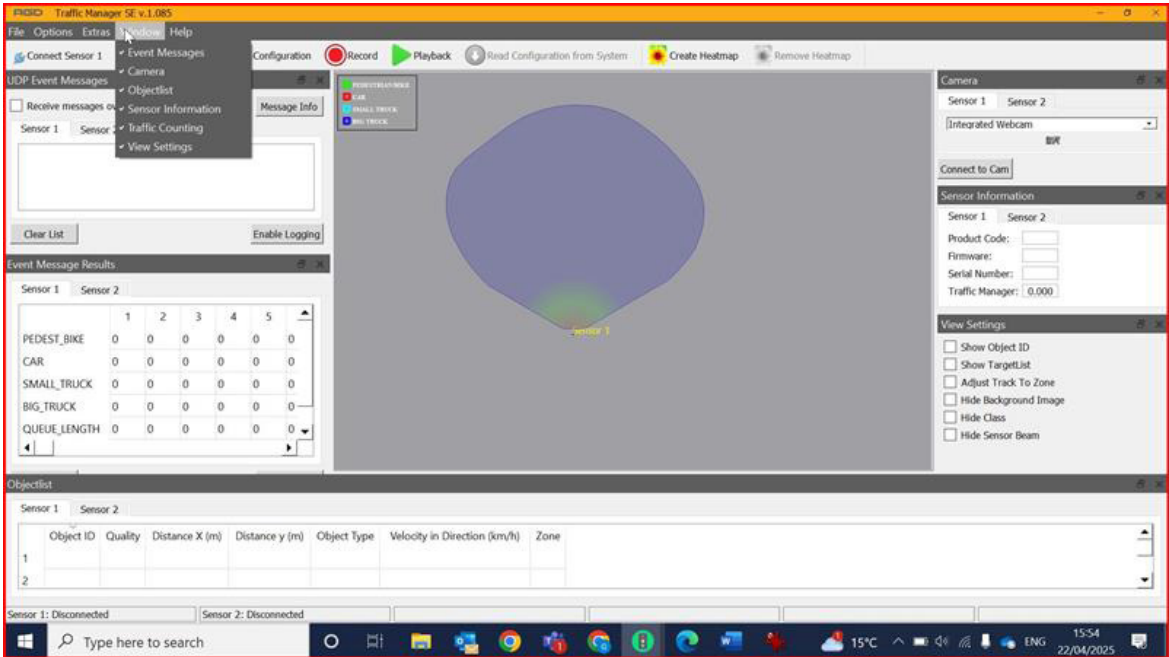


Position click the second point to get a measurement.



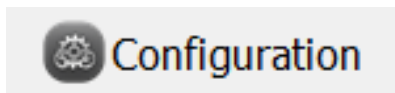
Launch Traffic Manager

Navigate to the Windows tab and disable all listed options



CONFIGURATION GUIDE

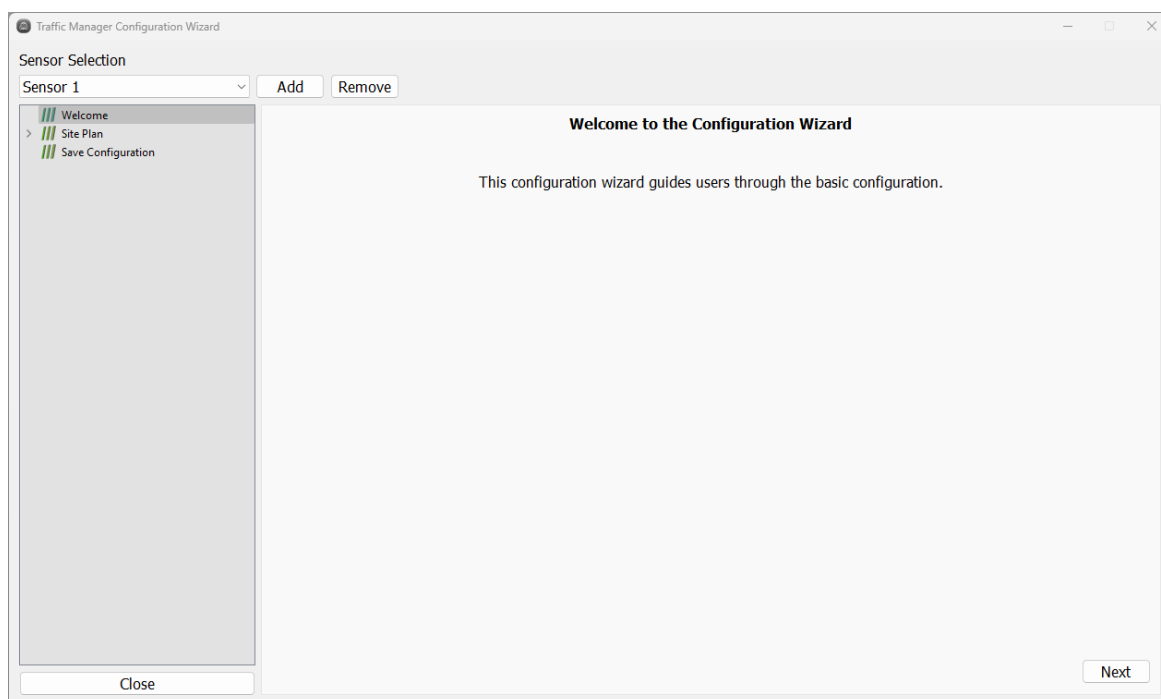
Open the configuration wizard by clicking on the 'Configuration' button.



The welcome screen and the overview of the configuration process are shown.

Open '**Site Plan**' to reveal the wizards stages.

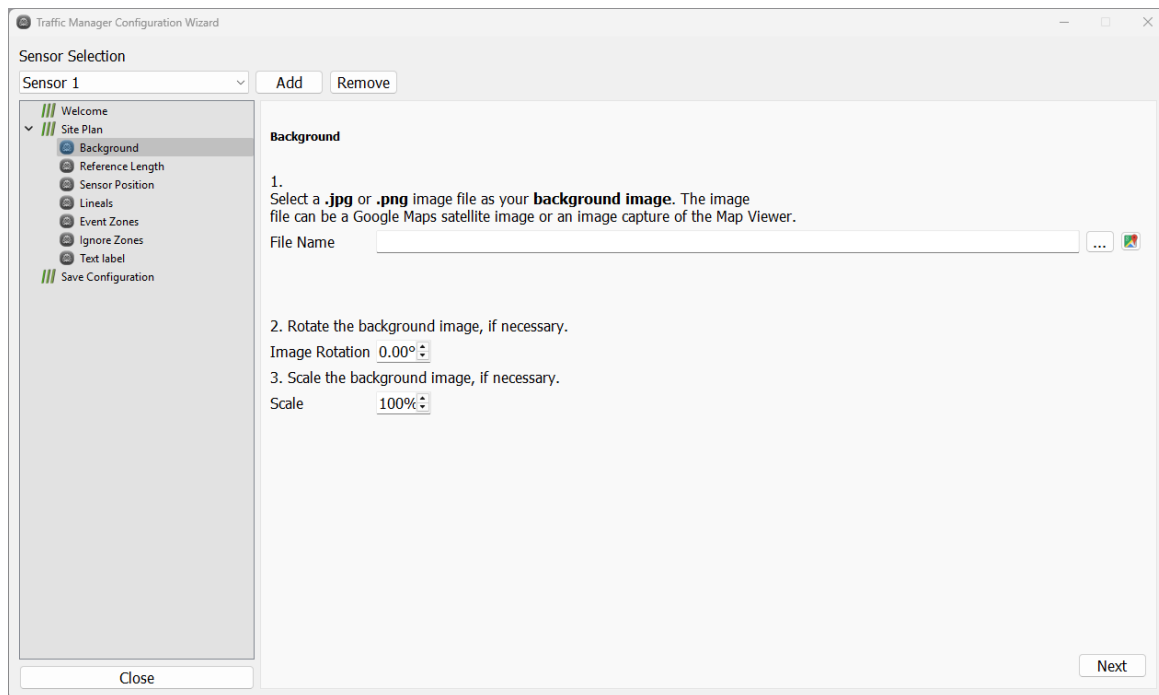
Click '**Next**' to navigate through the different configuration menus.



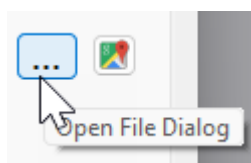
Background:

In the Background Menu an image of the scenery can be loaded. This is the basis for positioning your sensor(s) and defining the event zones for your application.

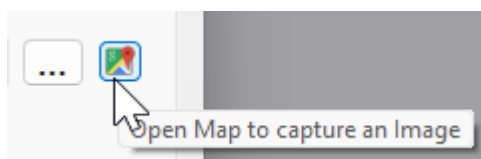
Hint: Rotate and Scale are available for the background image if necessary.



Option 1 Load a .jpg file or .png file from your hard drive.

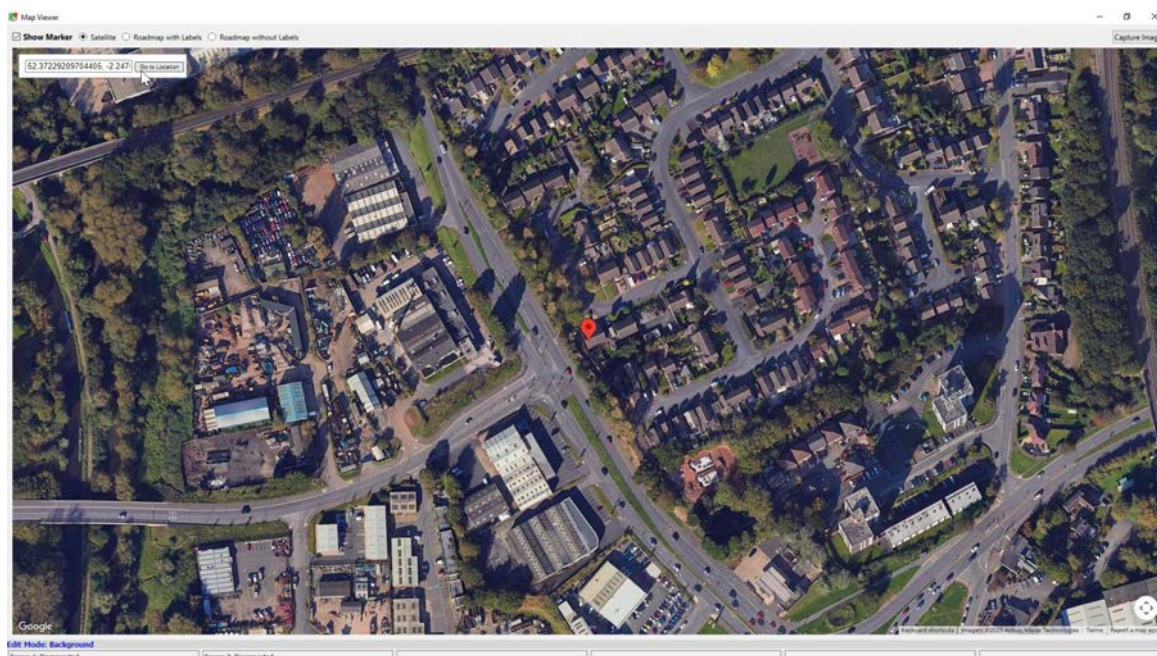


Option 2 Open Google Maps with the built-in map viewer and capture the image for scenery configuration. The image is then automatically loaded into the scenery.



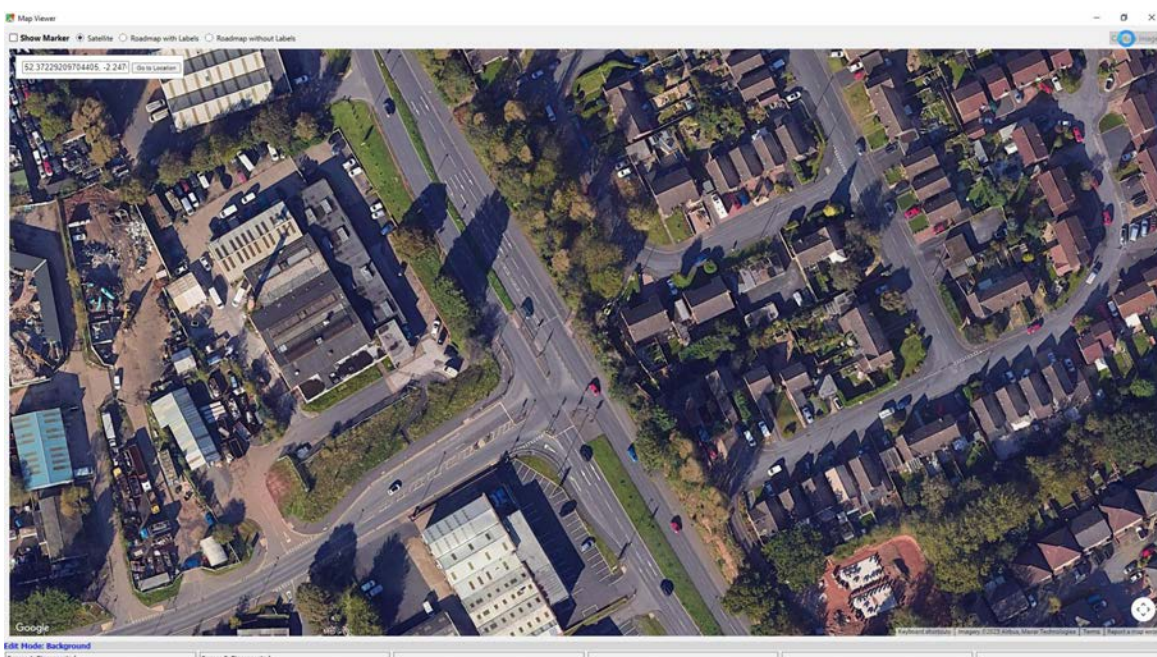
Paste LAT/LON into the Traffic Manager map viewer before selecting 'Go to Location'.

Hint: Can also type in the address or use a zip/post code.

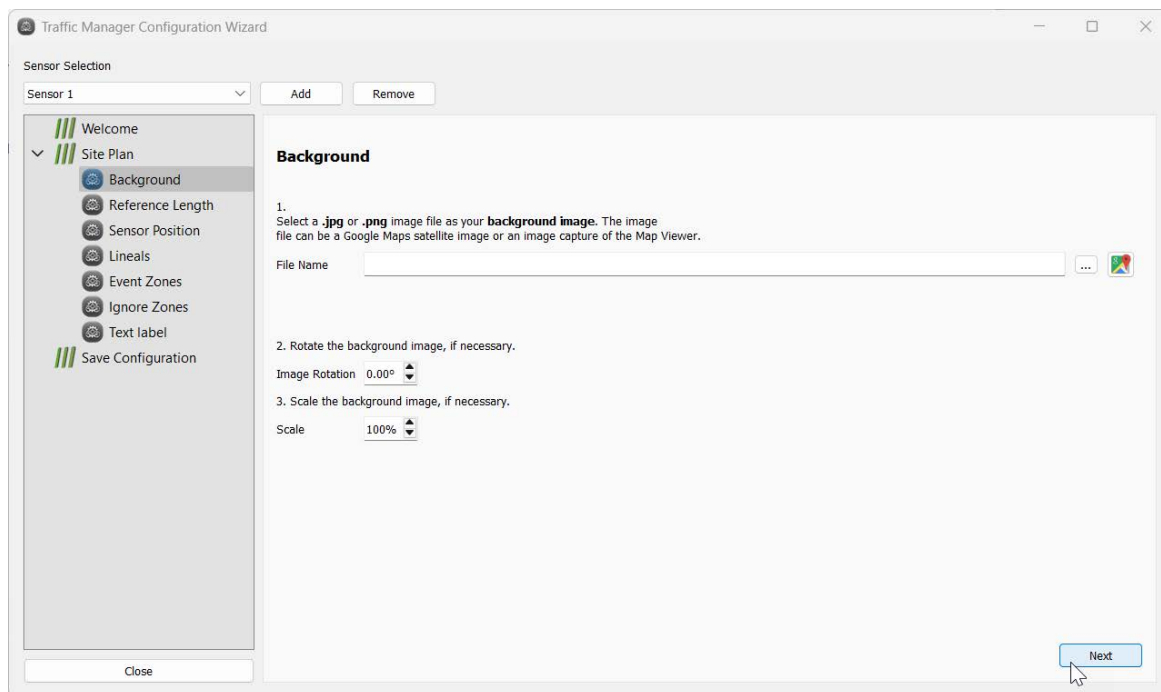


If required, further scroll and zoom to location before selecting 'Capture Image'.

Hint: Switch off 'Show Marker' if not required.



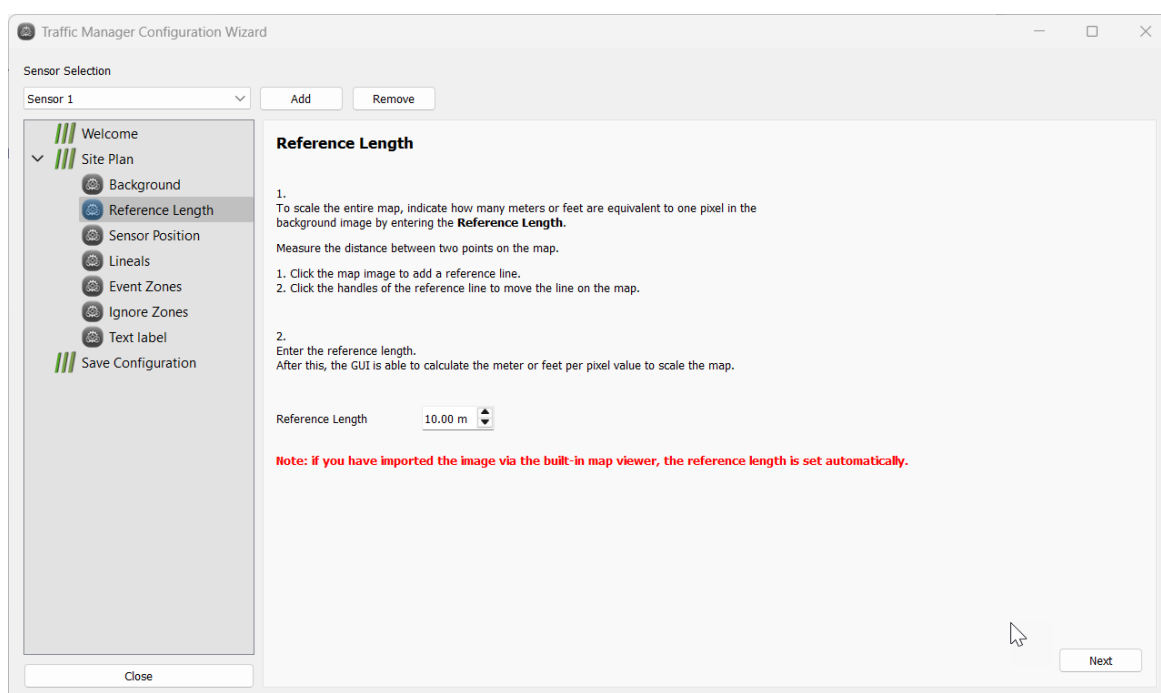
Once the image is captured, click 'Next' to progress to the next stage of the configuration wizard.



Reference Length:

Traffic Manager needs a reference length set correctly, otherwise measured objects and radar coverage do not match to the image.

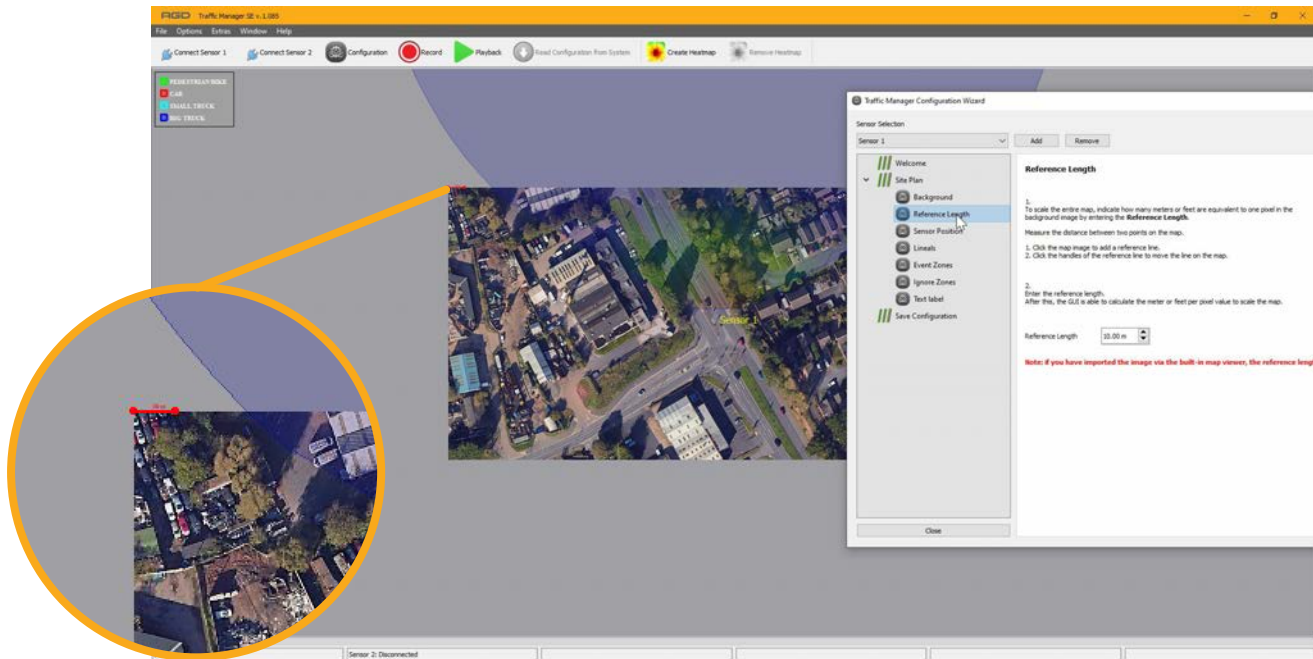
You can either measure the distance between two points by yourself or use Google Maps built-in functionality.



Selecting 'Reference Length' in the configuration wizard overlays the reference line top left of the map.

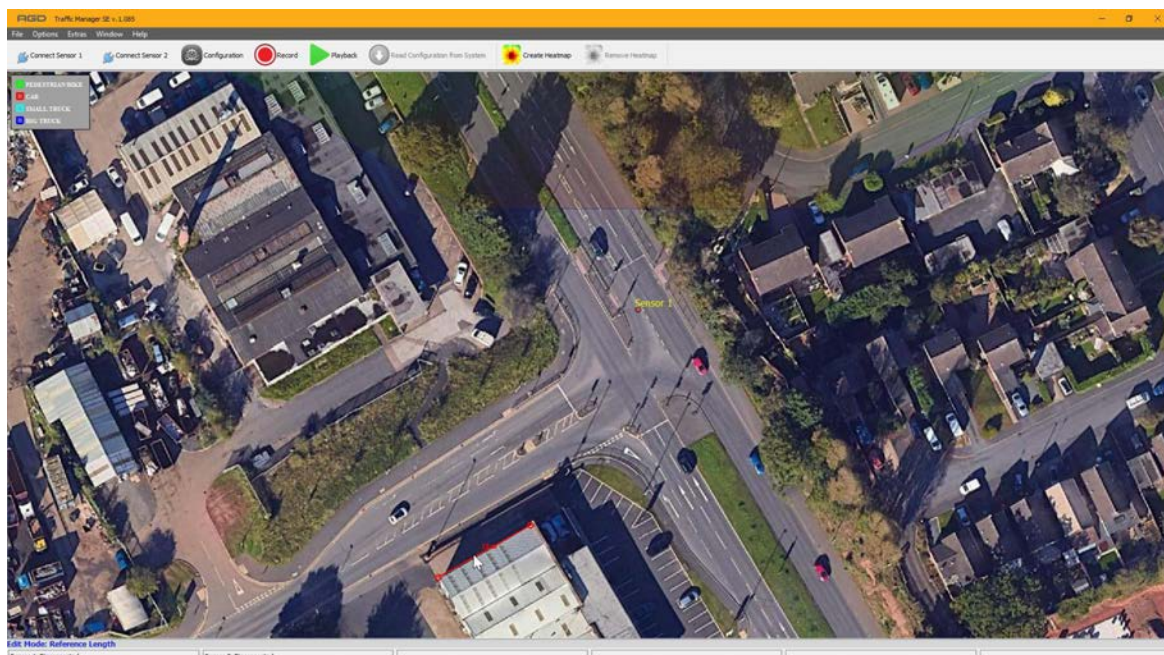
Best Practice: Always add Reference Length.

Google Maps provides accurate dimensions, but once imported into Traffic Manager, the image size may vary depending on screen settings.



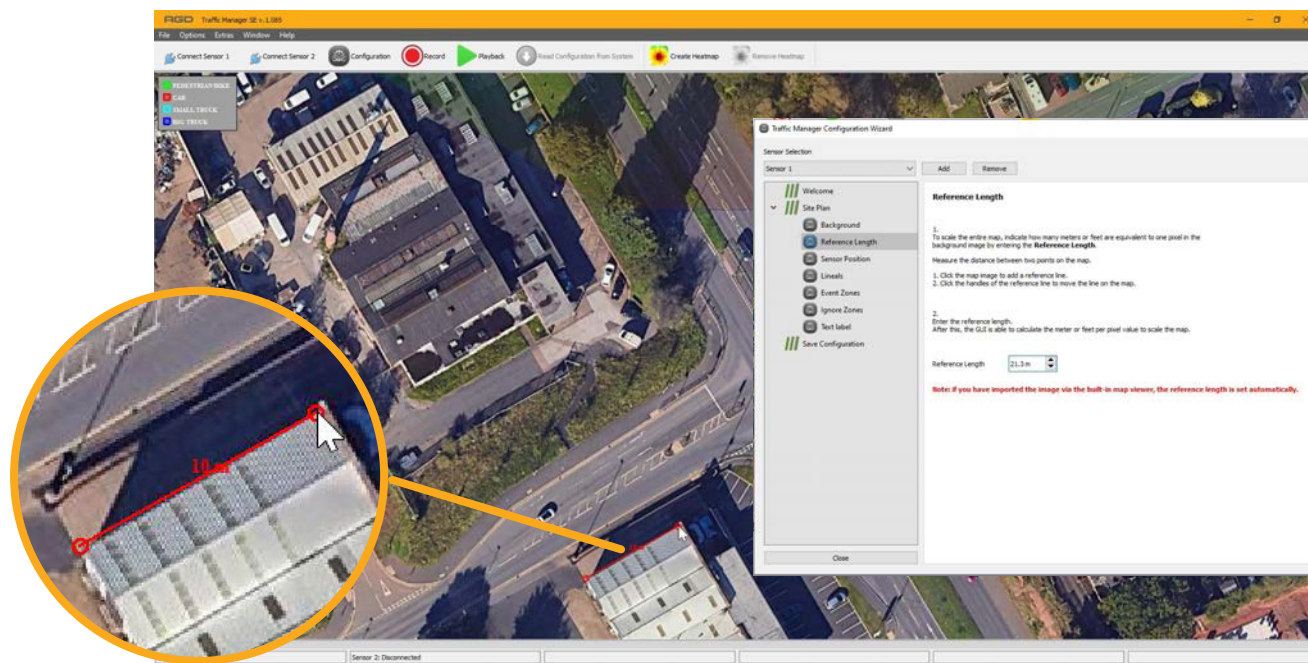
Drag the end points of the reference line to the same two points measured in Google maps.

Note the measurement discrepancy.



Enter the correct length between the two points to match Google maps.

This correctly scales measured objects and radar coverage to the image.



Sensor Position:

Use Up/Down and Left/Right Buttons to place the sensor's virtual position (red point) in the background image to the exact location where the AGD 352 is installed.

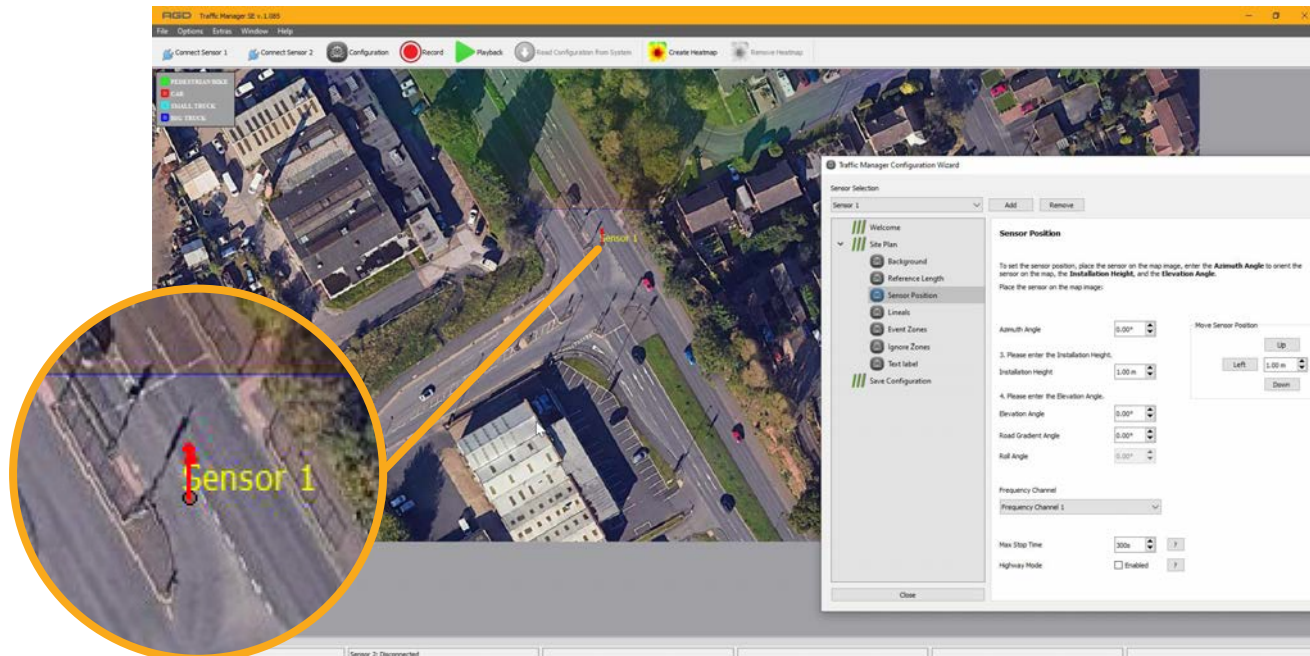
Then, set the installation height.

The elevation angle will be read from the sensor and corrected by the road gradient angle.

The screenshot shows the 'Traffic Manager Configuration Wizard' window, specifically the 'Sensor Position' step. On the left is a sidebar with a tree view containing 'Welcome', 'Site Plan', and several sub-items: 'Background', 'Reference Length', 'Sensor Position' (which is selected and highlighted), 'Lineals', 'Event Zones', 'Ignore Zones', and 'Text label'. Below this is a 'Save Configuration' button. The main area is titled 'Sensor Position' and contains instructions: 'To set the sensor position, place the sensor on the map image, enter the Azimuth Angle to orient the sensor on the map, the Installation Height, and the Elevation Angle. Place the sensor on the map image: 1. Click the map image to add the sensor. 2. Drag the sensor to the desired position in the map. The sensor is aligned to the north automatically.' Below the instructions are several input fields: 'Azimuth Angle' (0.00°), 'Installation Height' (1.00 m), 'Elevation Angle' (0.00°), 'Road Gradient Angle' (0.00°), and 'Roll Angle' (0.00°). To the right of these fields is a 'Move Sensor Position' dialog box with 'Up', 'Down', 'Left', and 'Right' buttons, and a '1.00 m' distance indicator. At the bottom of the main area are 'Frequency Channel' (Frequency Channel 1), 'Max Stop Time' (300s), and 'Highway Mode' (Enabled). A 'Next' button is at the bottom right, and a 'Close' button is at the bottom left.

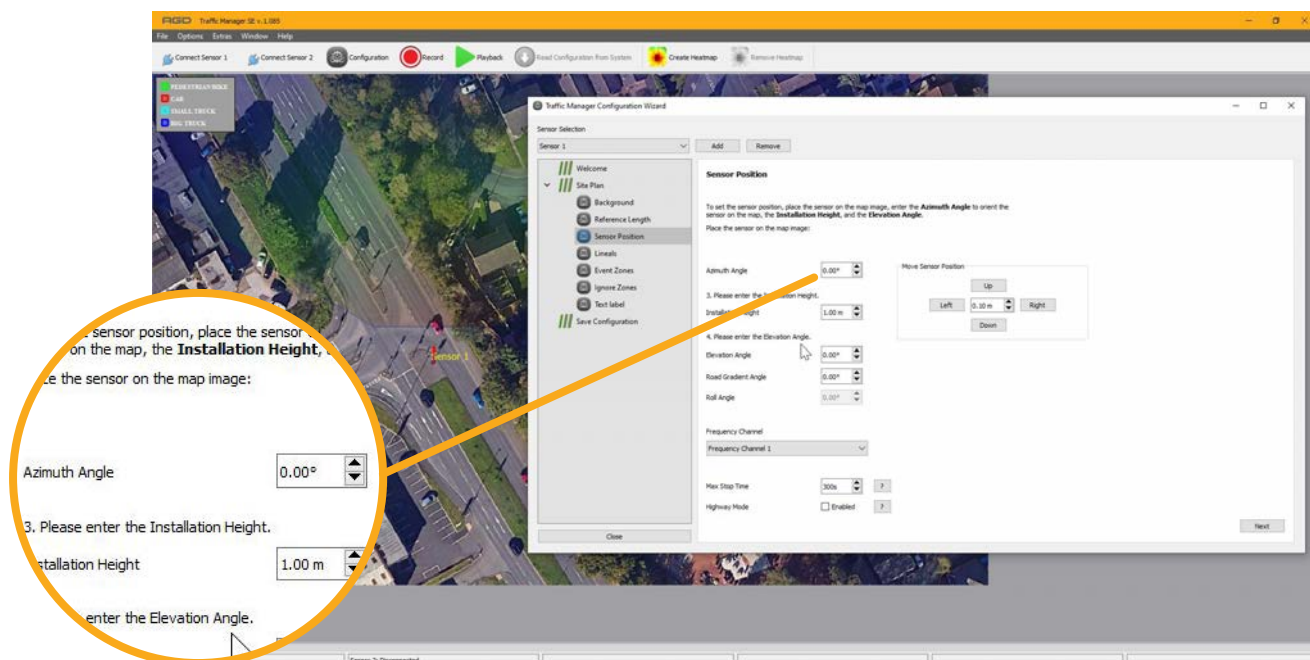
Alternatively for a rough step, manually click on the sensors red point to scroll into position.

Using the 'Move Sensor Position' options to fine tweak.

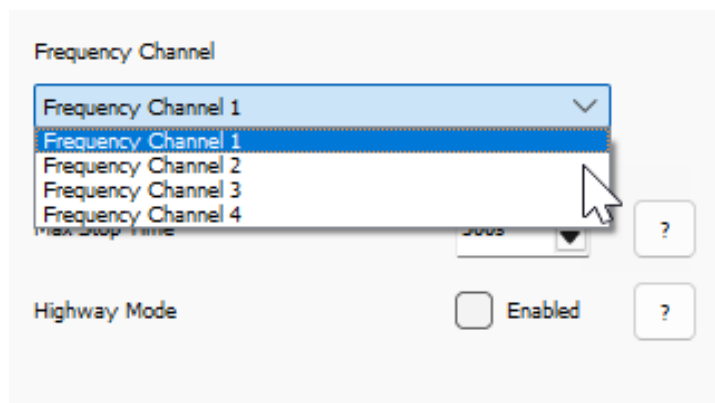


Select the sensors end point to manually rotate the radar's angle.

Use the 'Azimuth Angle' option to fine tune.



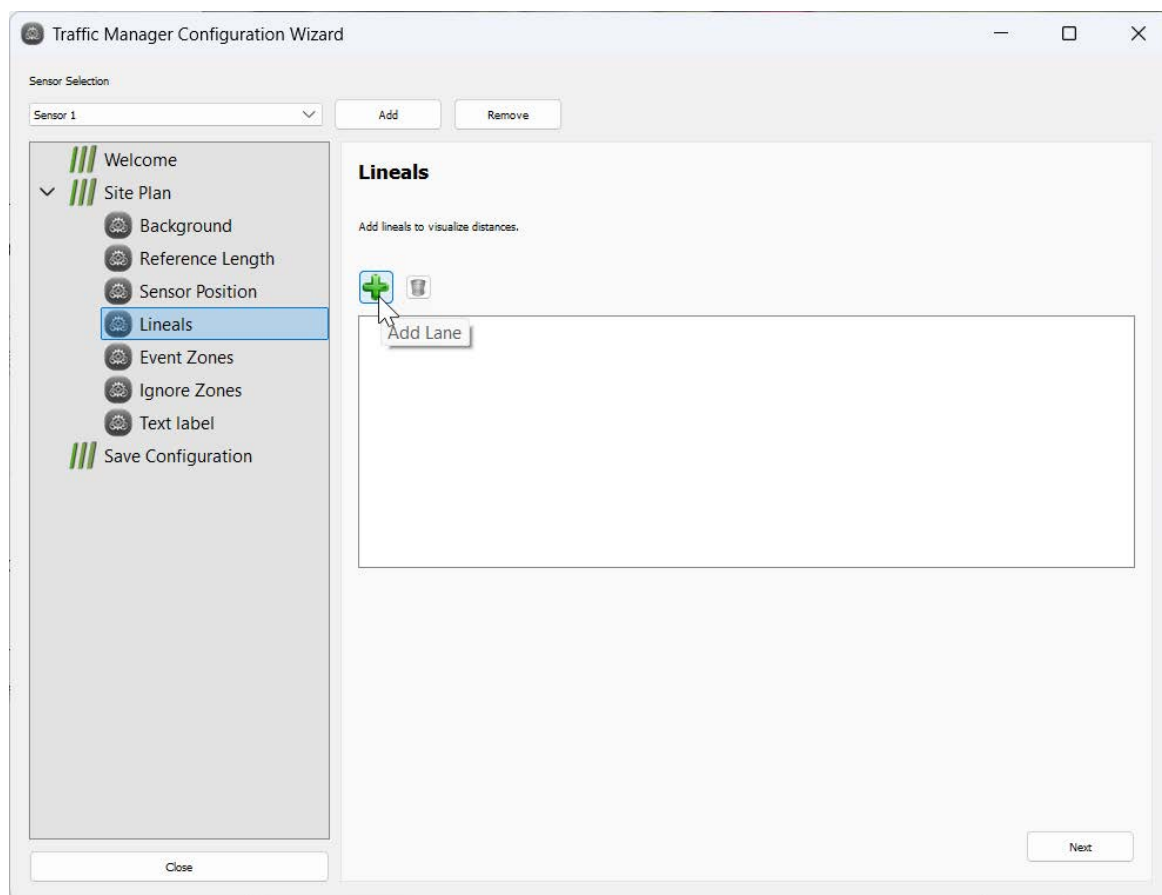
Hint: If you use more than one sensor, each sensor has to be set on a different frequency channel to avoid interference.



Lineals:

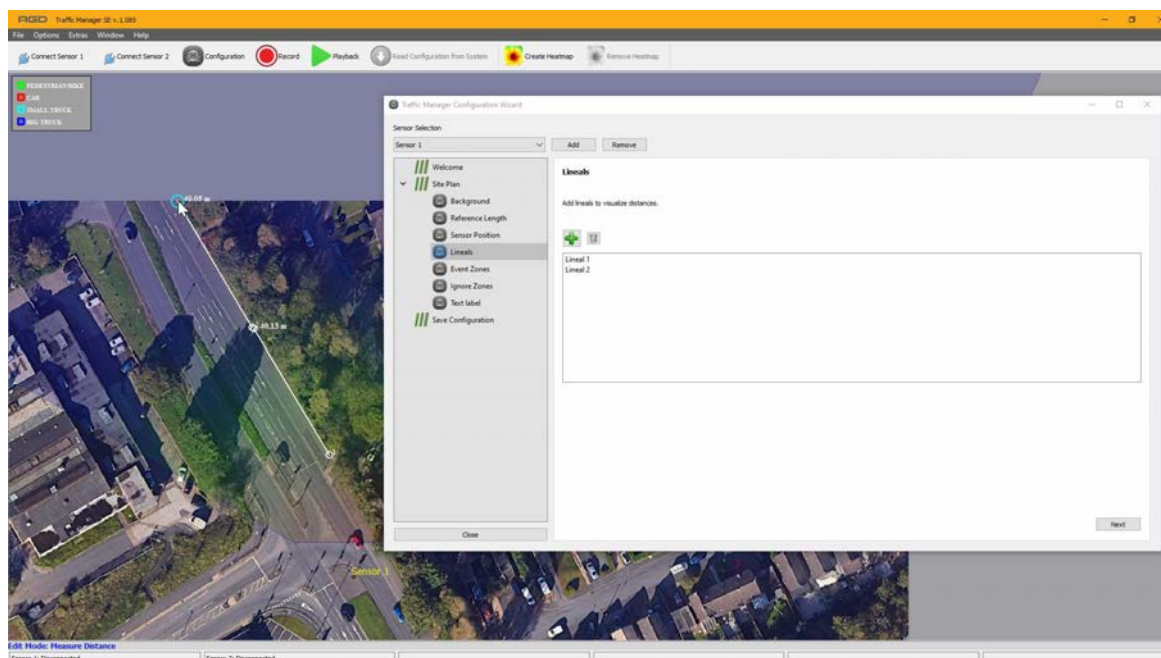
Lineals can be used to visualize distances in the configuration.

Click 'Add Line' icon to create.



Multiple lines can be added.

Especially useful when measuring for loop/event zone replication.



Event Zones:

Event zones are defined to generate event messages when an object is located within this zone. Further, you can add conditions such as speed, class, direction, message delay and extension along with ETA.

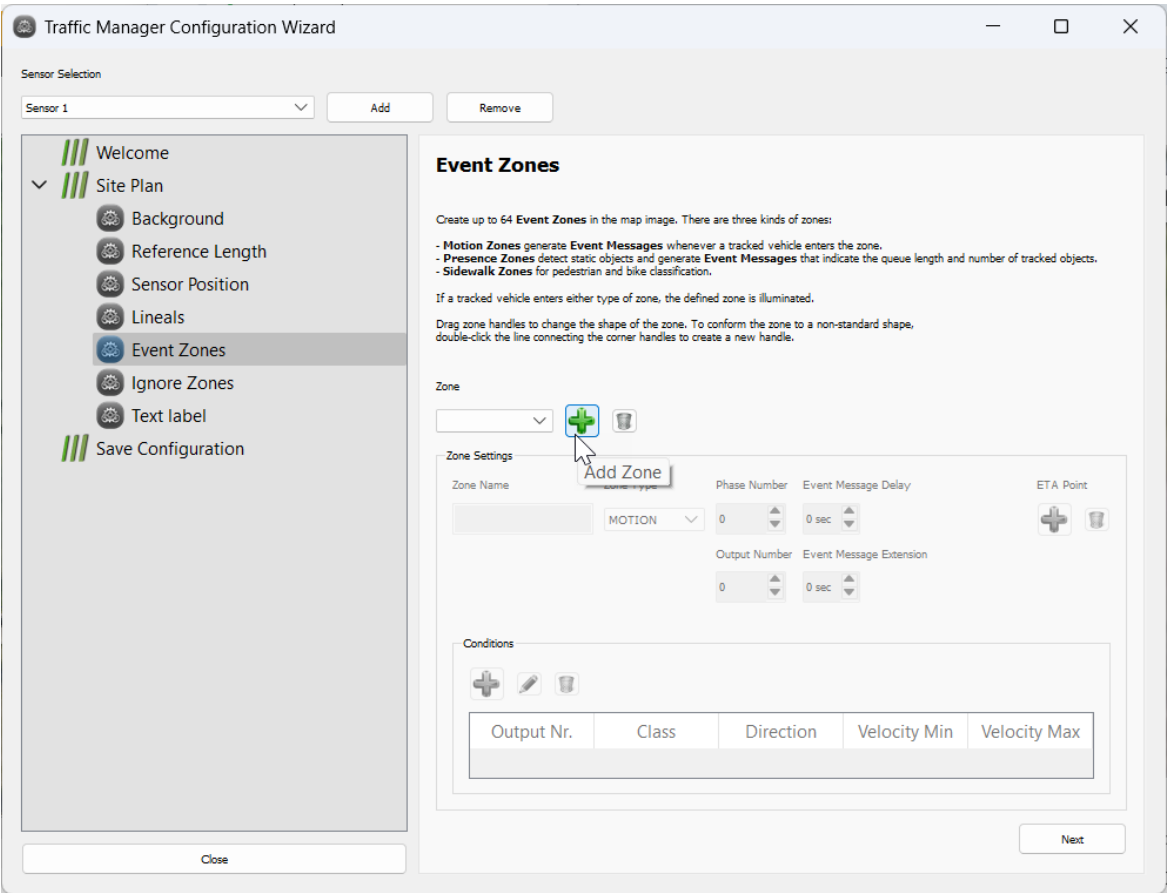
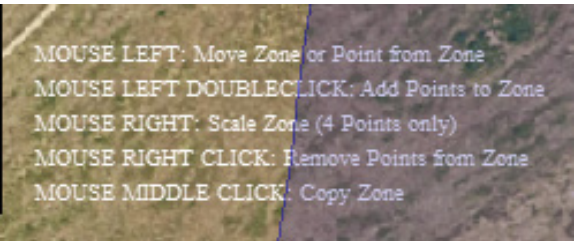


Chart describes mouse usage.

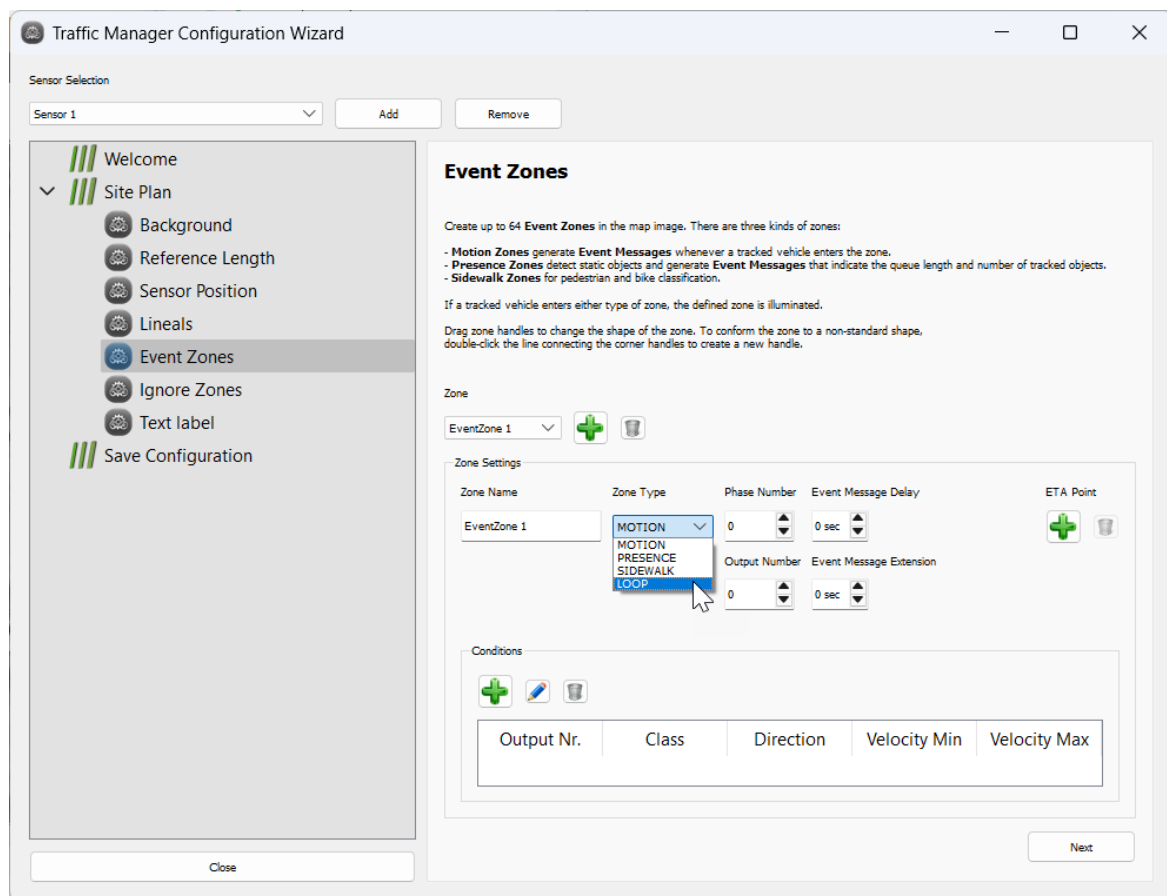


There are four types of zones:

- Motion Zone: A message will be sent each time an object enters an event zone. (ETA used)
- Presence Zone: A message will be sent each time at least one static object is in the event zone.
- Sidewalk Zone: This zone is for classification (pedestrian/bike) only and will not generate event messages.

For use with J8 Interface Card

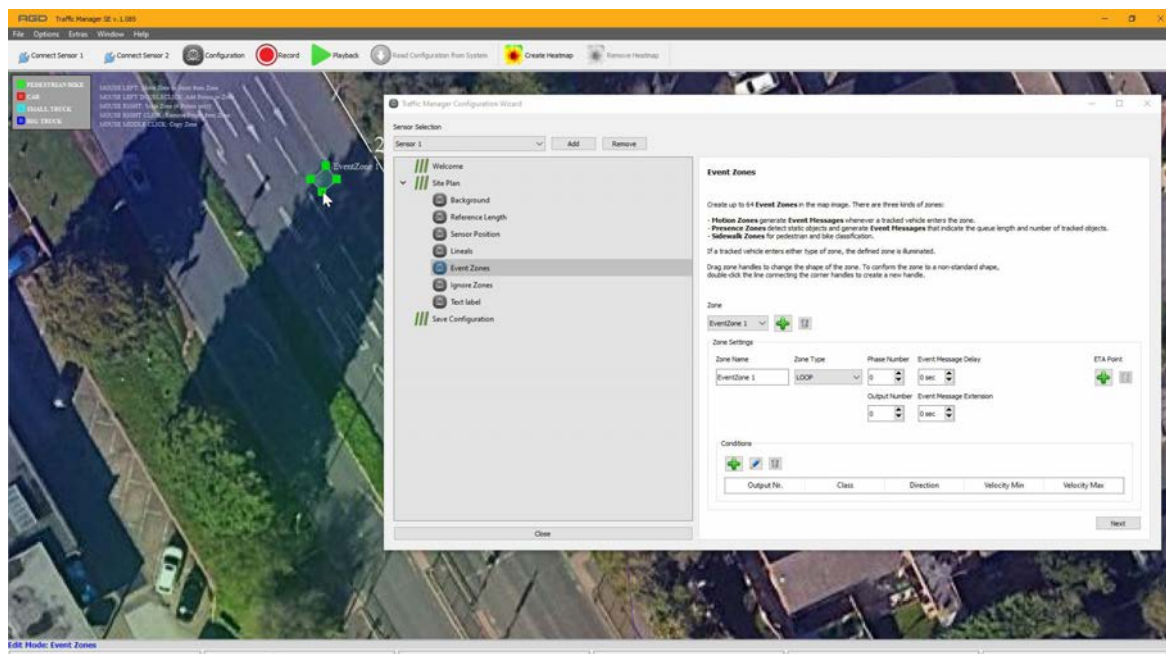
Loop Zone: Combines both Motion and Presence in a zone.



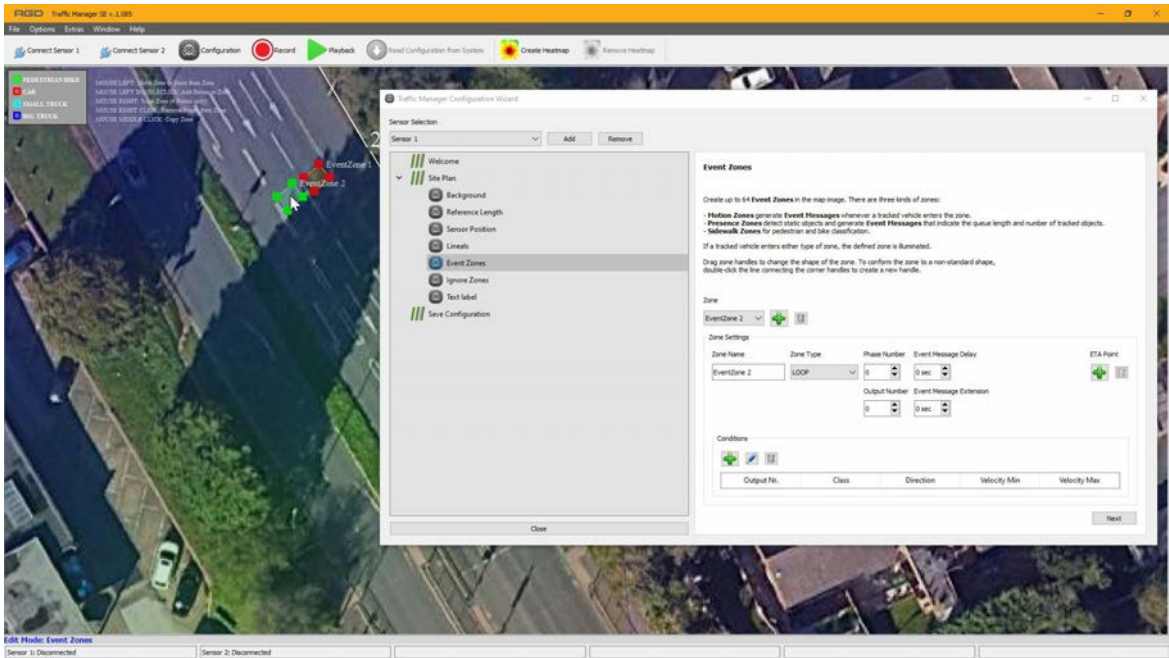
Condition: Assign one or more conditions to specify event message triggering such as direction, velocity and class type.

Once added, the event zone can be moved into position and adjusted by clicking and dragging the corner points.

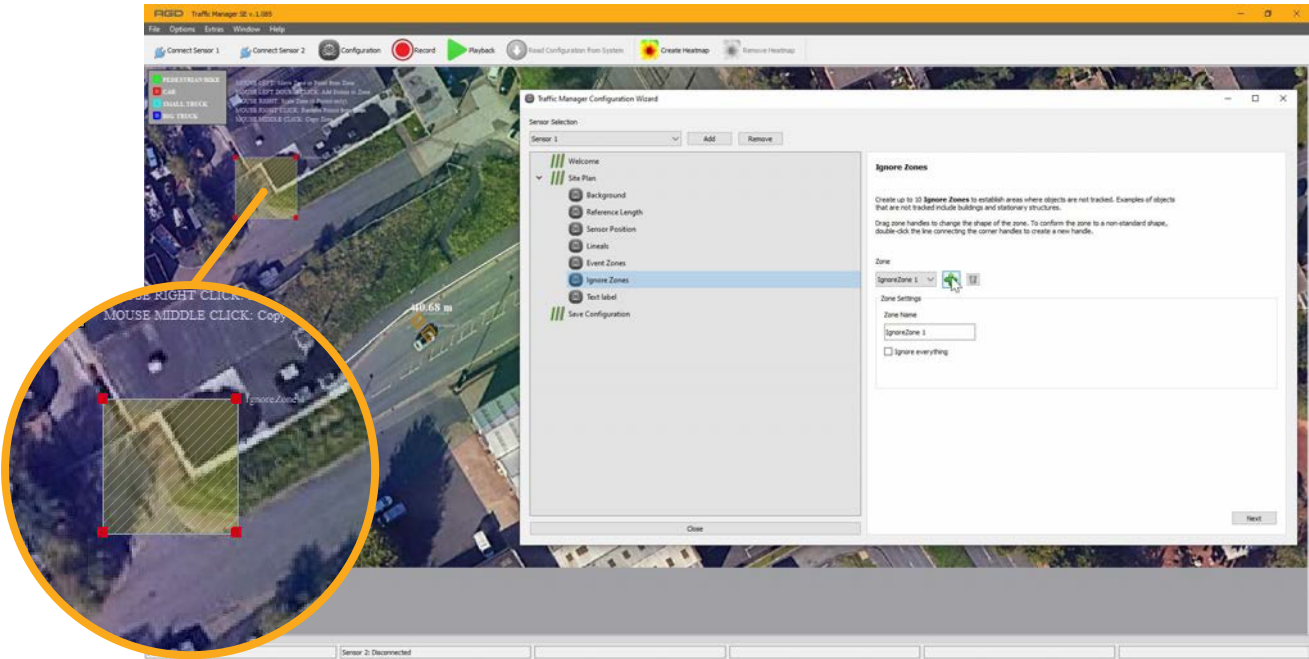
Hint: Left mouse double click on the lines of the event zone to add more points (max. 10) or remove points with right mouse click.



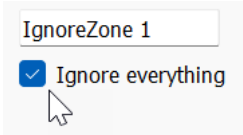
To duplicate an event zone, click on the zone using the mouse wheel.



Ignore Zones:
You can define regions where objects shall not initialize new tracks. Place an ignore zone in the background image.

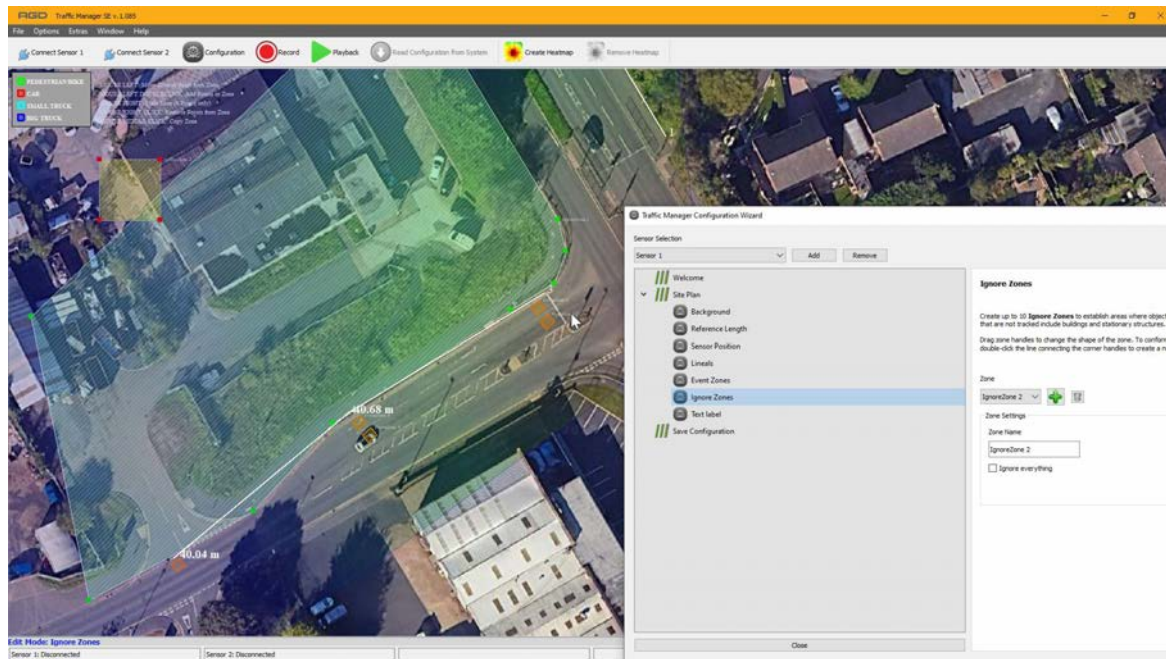


Hint: Enable 'Ignore everything'



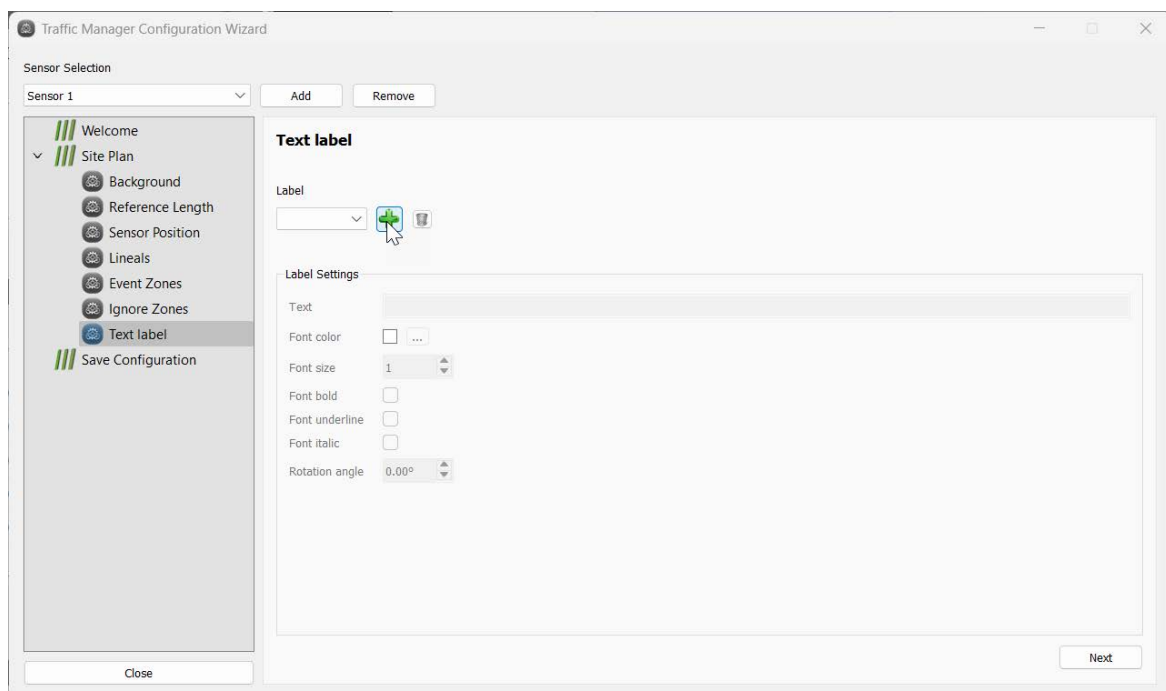
The shape of the ignore zone can be adjusted adding extra points.

Left mouse double click on the lines of the ignore zone to add more points (max. 10) or remove points with right mouse click.

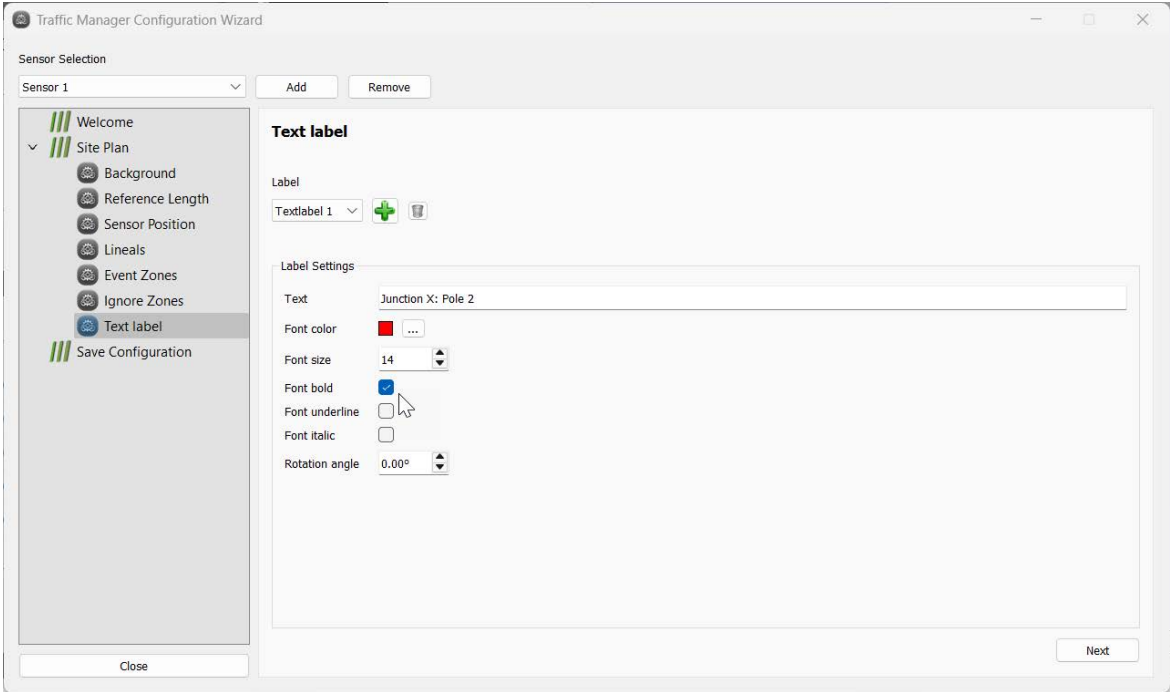


Test Label:

A text label can be used as a marking in the plot.



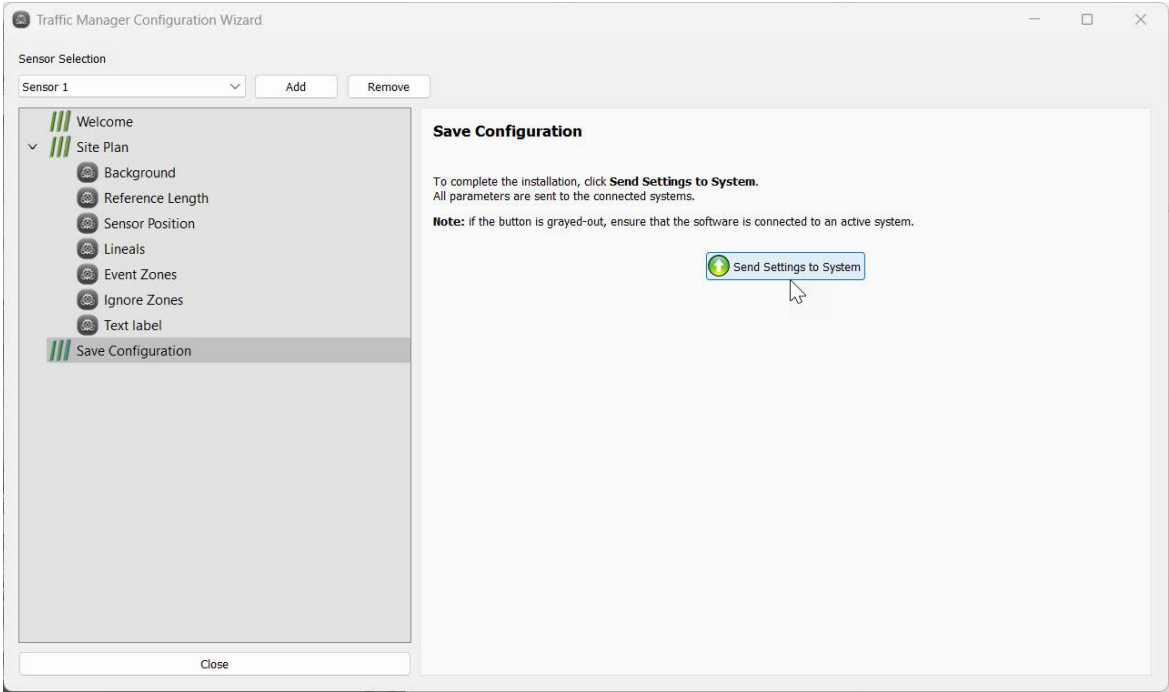
The labels have standard rich text options and can be rotated.



Label positions are adjustable by dragging the dot in the plot next to the text label



With the radar device connected, click ‘Send Settings to System’ to complete the device configuration.



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MORE EFFICIENT

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